

# Electromagnetism 2

## (spring semester 2025)

### Lecture 6

### Maxwell's equations in free space

- ❖ The continuity equation
- ❖ Modification of Ampere's law for non-steady currents
- ❖ The displacement current
- ❖ Maxwell's equations of electrodynamics in free space

# Previous lectures

- ❖ Our current (still incomplete) understanding of the equations of electromagnetism *in free space*:

Gauss law (*universally valid*)

$$\nabla \vec{E} = \rho / \epsilon_0$$

Faraday's law (*universally valid*)

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Absence of magnetic poles  
(*universally valid*)

$$\nabla \vec{B} = 0$$

Ampere's law (*static field only*)

$$\nabla \times \vec{B} = \mu_0 \vec{j}$$

- ❖ Variation of magnetic field gives rise to electric field.
- ❖ Does variation of electric field give rise to magnetic field?

# The continuity equation

## Conservation of electric charge:

any variation of charge within a fixed volume is due to charges flowing across the surface

$$\int_S \vec{j} d\vec{S} = -\frac{d}{dt} \int_V \rho dV$$

Unit on both sides: [C/s=A]

Divergence theorem:  $\int_S \vec{j} d\vec{S} = \int_V \nabla \cdot \vec{j} dV$

Conservation of charge in differential form:  
(the *continuity equation*)

$$\nabla \cdot \vec{j} = -\frac{\partial \rho}{\partial t}$$

Let's take the divergence of both sides of Ampere's law:

$$\underbrace{0 = \nabla(\nabla \times B)}_{\text{T1 from lecture 2}} = \underbrace{\mu_0 \nabla \cdot \vec{j}}_{\text{Continuity equation}} = -\mu_0 \frac{\partial \rho}{\partial t}$$

Therefore, Ampere's law applies to **steady currents only**  
(  $\partial \rho / \partial t = 0$  ), and **requires generalisation**

# Generalised Ampere's law

To generalise Ampere's law for non-steady currents, let's modify its right-hand side to make its divergence zero.

Gauss law:  $\epsilon_0 \nabla \cdot \vec{E} - \rho = 0$ . Differentiation over  $t$ :

$$0 = \epsilon_0 \nabla \cdot \left( \frac{\partial \vec{E}}{\partial t} \right) - \frac{\partial \rho}{\partial t} = \epsilon_0 \nabla \cdot \left( \frac{\partial \vec{E}}{\partial t} \right) + \nabla \cdot \vec{j} = \nabla \cdot \left( \underbrace{\epsilon_0 \frac{\partial \vec{E}}{\partial t} + \vec{j}}_{\text{Displacement current density}} \right)$$

We have found a quantity  $\left( \epsilon_0 \frac{\partial \vec{E}}{\partial t} + \vec{j} \right)$  which always has zero divergence and is therefore suitable for a modified Ampere's law.

The *Ampere-Maxwell law*:  $\nabla \times \vec{B} = \mu_0 \vec{j} + \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t} \quad (*)$

Not a proof: there are many ways of removing the contradiction. Any solenoidal field (i.e. such that  $\nabla \cdot \vec{u} = 0$ ) can be added to the right-hand side of (\*), still satisfying charge conservation.

# The displacement current

$$\nabla \times \vec{B} = \mu_0(\vec{j}_C + \vec{j}_D) = \mu_0\vec{j}_C + \varepsilon_0\mu_0 \frac{\partial \vec{E}}{\partial t}$$

$\vec{j}_C$ : conduction current density       $\vec{j}_D$ : displacement current density

A changing **E**-field produces **B**-field:

Maxwell's decisive step towards electrodynamics (**1865**).

It took **30** years after Faraday's discovery of EM induction to postulate the displacement current as a source of magnetic field.

Alternating current in a copper wire [conductivity  $\sigma = 6 \times 10^7 \text{ } (\Omega \cdot \text{m})^{-1}$ ]

Electric field:

$$\vec{E} = E_0 \sin(\omega t)$$

Conduction current density:

$$\vec{j}_C = \sigma \vec{E} = \sigma E_0 \sin(\omega t)$$

Displacement current density:

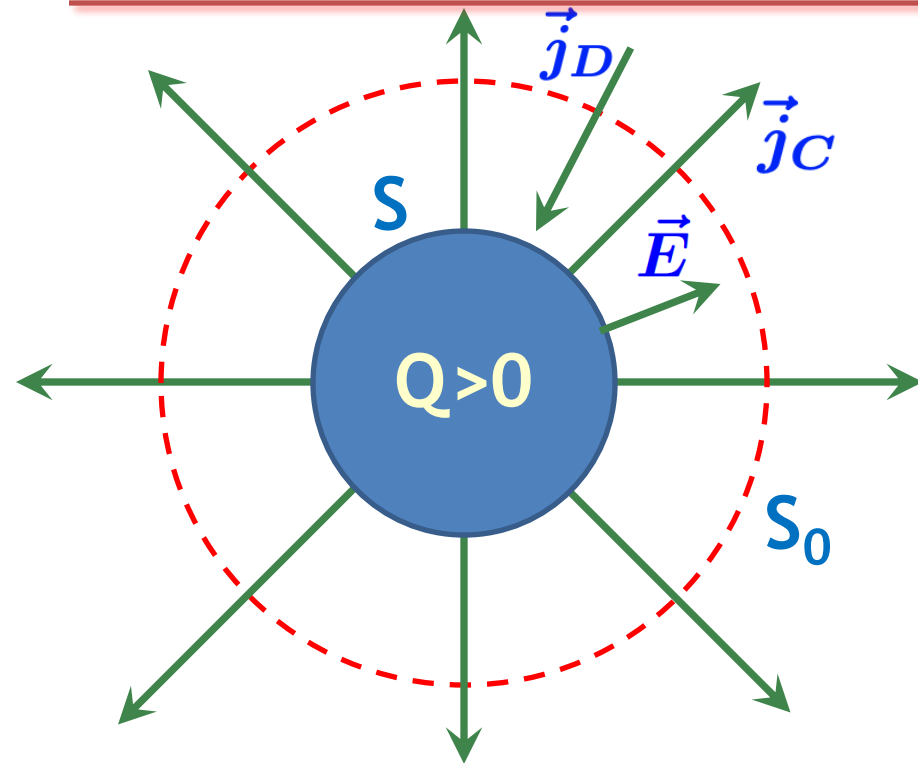
$$\vec{j}_D = \varepsilon_0 \partial \vec{E} / \partial t = \varepsilon_0 \omega E_0 \cos(\omega t)$$

The ratio of maximum max conduction to max displacement current:

$$\vec{j}_C^{\max} / \vec{j}_D^{\max} = \sigma E_0 / \varepsilon_0 \omega E_0 \sim 10^{19} \text{ s}^{-1} \omega^{-1} \gg 1,$$

i.e.  $\vec{j}_D$  is negligible for all frequencies used in practice.

# Example 1



A charged sphere discharging into external conductive medium.

By symmetry,  $\vec{j}_C$  is directed radially. What about the  $\vec{B}$  field?

By symmetry, tangential component  $B_t = 0$ , and radial component  $B_R$  is the same in each point of sphere  $S$ .

Assuming  $B_R \neq 0$  leads to  $\int_S \vec{B} d\vec{S} \neq 0$ . We conclude that  $\vec{B} = 0$ .

Ampere's law leads to  $\vec{j}_C = 0$ .

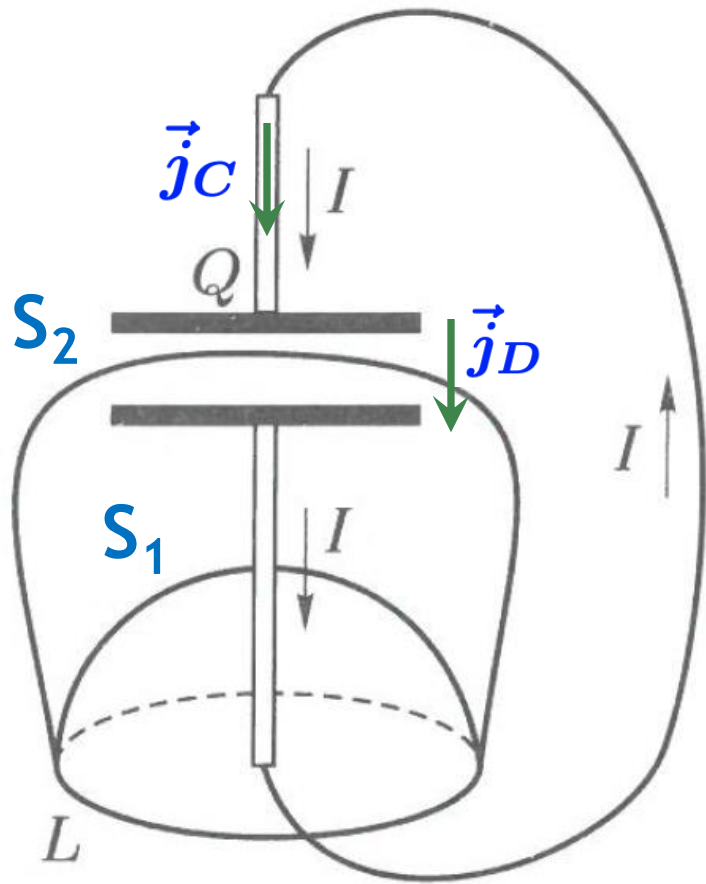
$\vec{E}$ -field at the surface of the sphere (*lecture 1*):  $E = Q / (4\pi\epsilon_0 R^2)$

Conduction current at surface  $S_0$  is balanced by displacement current:

$$I_D = I_C = \frac{dQ}{dt} = 4\pi\epsilon_0 R^2 \frac{\partial E}{\partial t}$$

$$J_D = I_D / (4\pi R^2) = \epsilon_0 \frac{\partial E}{\partial t}$$

# Example 2



Discharge of a parallel-plate capacitor:

$$\oint_L \vec{B} d\vec{l} = \mu_0 \int_S (\vec{j}_C + \vec{j}_D) d\vec{S}$$

- ❖ For the surface  $S_1$ , only the conduction current  $I_C$  contributes.
- ❖ For the surface  $S_2$ , there is no conduction current, therefore  $I_D = I_C$ .

Let's check explicitly the equality  $I_D = I_C$ :

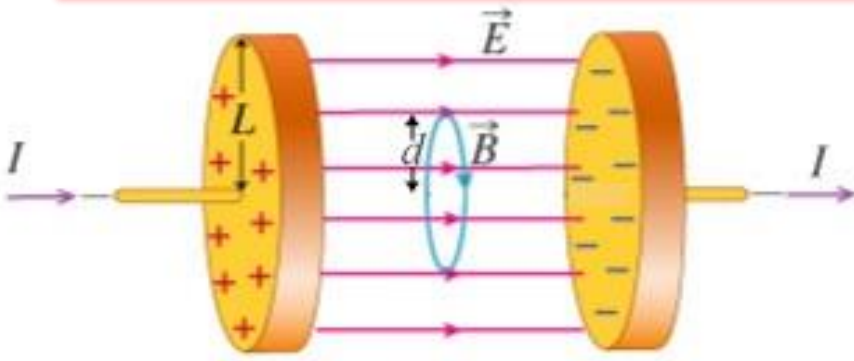
$$I_C = \frac{\partial Q}{\partial t} = A \frac{\partial \sigma}{\partial t} = A \epsilon_0 \frac{\partial E}{\partial t}$$

By definition,  $I_D = A \epsilon_0 \frac{\partial E}{\partial t} = I_C$

Lecture 1:  $E = \sigma / \epsilon_0$

# Example 3

[not discussed in the lecture]



A thin parallel plate capacitor with circular plates of radius **R** is being charged. Find the magnetic field **B(r)**.

Using axial symmetry, in the absence of conduction current ( $\mathbf{j}_C = 0$ ),

$$\oint_L \vec{B} d\vec{l} = \mu_0 \int_S (\vec{j}_C + \vec{j}_D) d\vec{S} = \epsilon_0 \mu_0 \int_S \frac{d\vec{E}}{dt}$$

Inside the capacitor ( $r < R$ ),

$$2\pi r B = \epsilon_0 \mu_0 \cdot \pi r^2 \frac{dE}{dt}$$

$$B(r) = \frac{1}{2} \epsilon_0 \mu_0 r \frac{dE}{dt}$$

Outside the capacitor ( $r \geq R$ ),

$$2\pi r B = \epsilon_0 \mu_0 \cdot \pi R^2 \frac{dE}{dt}$$

$$B(r) = \frac{1}{2} \epsilon_0 \mu_0 \frac{R^2}{r} \frac{dE}{dt}$$

# Maxwell's equations in free space

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Laws of electrodynamics in free space:

(remember them)

$$(M1) \quad \nabla \vec{E} = \rho / \epsilon_0$$

$$(M2) \quad \nabla \vec{B} = 0$$

$$(M3) \quad \nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

$$(M4) \quad \nabla \times \vec{B} = \mu_0 \vec{j} + \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t}$$

Displacement current density:  $\vec{j}_D = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$

The continuity equation,  $\nabla \cdot \vec{j} = - \frac{\partial \rho}{\partial t}$ , follows from (M1) and (M4). 8

# Discussion and summary

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- ❖ Maxwell's equations in free space (2 scalar + 2 vector) are equivalent to 8 scalar equations with 10 variables ( $E_x, E_y, E_z, B_x, B_y, B_z, j_x, j_y, j_z, \rho$ ).
- ❖ Maxwell's equations must be complemented by the equations characterising the media. These will be discussed in lectures 7–12.
- ❖ The equations are not symmetric wrt electric and magnetic fields:
  - ✓ no magnetic poles as sources of  $B$  field (M2);
  - ✓ no magnetic currents as sources of  $E$  field (M3).
- ❖ For constant fields ( $\partial E/\partial t = \partial B/\partial t = 0$ ), two independent groups,
  - ✓ electrostatics:  $\text{div } E = \rho/\epsilon_0$ ;  $\text{curl } E = 0$ ;
  - ✓ magnetostatics:  $\text{div } B = 0$ ;  $\text{curl } B = \mu_0 j$ .