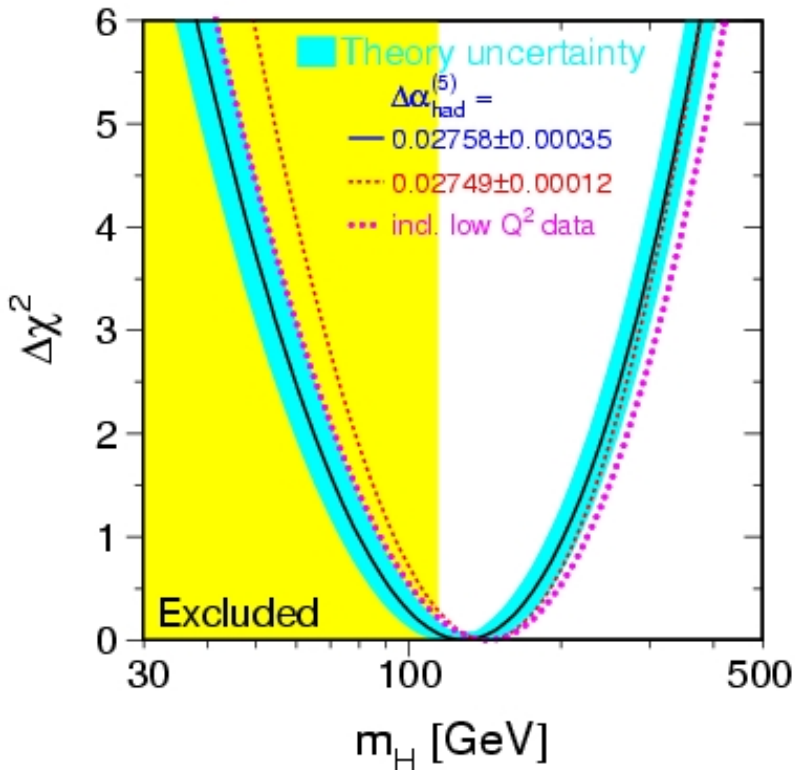


Last Lecture: Probability Distributions ... Binomial
 ... Poisson
 ... Gaussian
 : Central Limit Theorem ... why Gaussians are "normal"
 ... why for N measurements,
 $\sigma(N) = \sigma(1)/\text{sqrt}(N)$



Today's lecture:

Extracting Information from Data:

- ... Estimation
- ... Fitting
- ... Likelihood

(See Barlow's text book for a more detailed discussion)

Case Study Reminder

- 10 minutes + 5 for questions is not long!
- Please focus on experimental and phenomenological aspects (i.e. things studied on this course) rather than giving too much theory detail
- Marks awarded (with equal weight) for:
 - Presentation
 - Scientific Content
 - Understanding Conveyed
 - Answers to questions
- Assessed by PRN and a couple of friendly Ph.D. students
- Aim to be (reasonably) fun, interesting and educational ...

Case Study Schedule

1. Monday 1 December

Tony: Neutrinoless double beta decay experiments

Jack: The Totem experiment / forward physics @ LHC

2. Friday 5 December

Sukhbinder: Triggering events at the LHC

Pat: Heavy Ion experiments and the Quark-Gluon Plasma

Amelia: Evidence for neutrino mass from SuperK & elsewhere

3. Monday 8 December

Alex: The top quark discovery at the Tevatron

Rory: Searching for Supersymmetry at the LHC

Reminder: The Central Limit Theorem

When multiple measurements are added together:

$$\langle x \rangle = \mu_1 + \mu_2 + \dots + \mu_N$$

$$V(x) = V_1 + V_2 + \dots + V_N$$

$P(x) \rightarrow$ Gaussian

$$\sigma \sim \frac{1}{\sqrt{N}}$$

Examples of the CLT (i.e. Gaussian distributions) are everywhere!... eg people's heights are governed by many environmental & genetic factors, but overall distribution is Gaussian

There are counter-examples, eg people's weights ... because a single factor (food intake) dominates and gives a skew

Summary of Probability Distributions

Main points from last lecture ...

- Binomial distribution (yes/no situations, eg effic's)
- Poisson distribution (numbers of events observed if we know the mean number or 'expectation')
- Both look more and more Gaussian as stats improve

Distributions you need to know about in high energy physics

- Gaussian
- Poisson, Binomial
- Everything else (Top hat, Breit-Wigner, Landau, Gamma, Student's t, χ^2 ...)

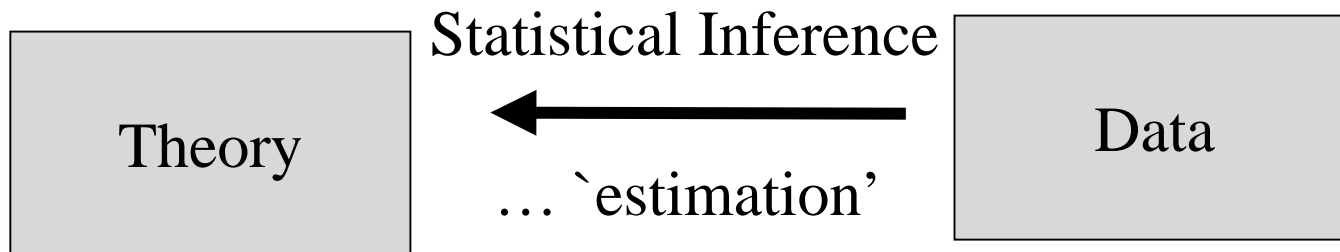
Extracting Information from Data: Estimation and Fitting

How to decide whether our data are well described by a model?

How to extract 'best estimates' of model parameters from the data?



Rather than predicting data using theory ...



... we want to extract best estimates of theory param's from data

What is an Estimator?

Formal Definition:

An estimator is a quantity extracted as a function of the data which gives a numerical value for a property of the parent distribution.

e.g. some possible estimators for the mean of a set of N points

$$\{x\} = x_1, x_2, x_3 \dots x_N:$$

$$\hat{\mu}(\{x\}) = x_1 \quad \hat{\mu}(\{x\}) = \frac{x_{\max} + x_{\min}}{2} \quad \hat{\mu}(\{x\}) = \frac{1}{N} \sum_i x_i$$

e.g. estimators for the variance of a set of N points $\{x\}$:

$$\hat{V}(\{x\}) = \frac{1}{N} \sum_i (x_i - \hat{\mu})^2 \quad \hat{V}(\{x\}) = \frac{1}{N-1} \sum_i (x_i - \hat{\mu})^2$$

.... some estimators are better than others!

Desired Properties of Estimators

1. **Consistency.** An estimator is consistent if it tends towards the true value as $N \rightarrow \infty$.
2. **Unbiased.** An estimator is unbiased if its expectation value is equal to the true value.
3. **Efficient.** An estimator is efficient if its variance is small.

- Of examples on previous page, optimal choices are ...
- Easy to see that these are consistent and unbiased.
- Efficiency is more complicated (see 'Minimum Variance Bound' in text books)



$$\hat{\mu}(\{x\}) = \frac{1}{N} \sum_i x_i$$

$$\hat{V}(\{x\}) = \frac{1}{N-1} \sum_i (x_i - \hat{\mu})^2$$

Often, we want to "estimate" much more complicated things than means and variances - e.g. α_s from lots of different observables in jet data ... need generalised estimation methods

The Likelihood Function

Suppose we have a set of data points $\{x_1, x_2, x_3 \dots x_N\}$ taken from a "parent" probability distribution characterised by a parameter A , to be estimated.

e.g. A might be the Higgs mass and $\{x_i\}$ might be LEP and TeVatron data which we believe obey the Standard Model

Define $P(x_1; a)$ = Probability of getting the result x_1 if $A=a$
Then the 'likelihood' of $A=a$ is just the combined probability that we get the set of points $\{x_i\}$ if $A=a$... i.e...

$$L(x_1, x_2, \dots, x_N; a) = P(x_1; a)P(x_2; a) \dots P(x_N; a) = \prod_{i=1}^N P(x_i; a)$$

Often more practical to work with 'log likelihood'

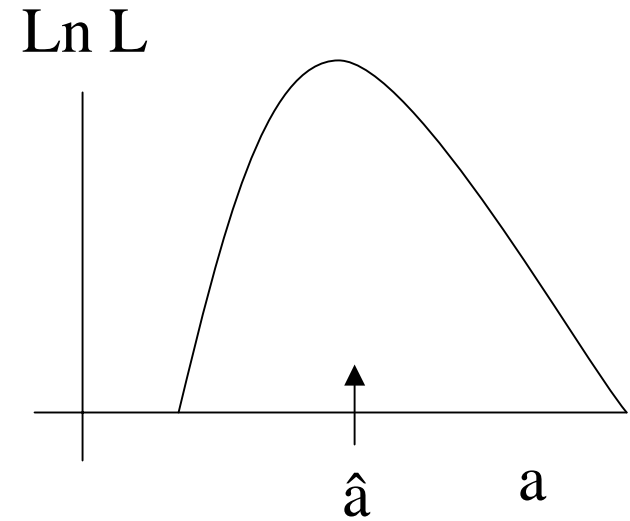
$$\ln L(x_1 \dots x_N; a) = \sum_{i=1}^N \ln P(x_i; a)$$

Maximum Likelihood

To get best estimate \hat{a} for a , just maximise the (log) likelihood of obtaining measured data with respect to a

... well defined general estimation method...

The maximum likelihood estimator \hat{a} is the value of a which makes the probability of the observed results as large as possible.



$$\hat{a} \text{ is obtained by the condition } \left. \frac{d \ln L}{da} \right|_{a=\hat{a}} = 0$$

Maximum likelihood has lots of nice properties

.... consistent, unbiased and efficient for large N

.... Invariant: i.e, if we extract \hat{a} and u is a function of a , $\hat{u}=u(\hat{a})$

.... nice programs exist to do max / minimisation in real problems!

Numerical Max Likelihood Example

Suppose we have a sample $\{x_i\} = 0.89, 0.03, 0.50, 0.36, 0.49 \dots$
... which we know comes from a parent distribution with
 $P(x) \propto 1+a(x-0.5)$, but a is unknown.

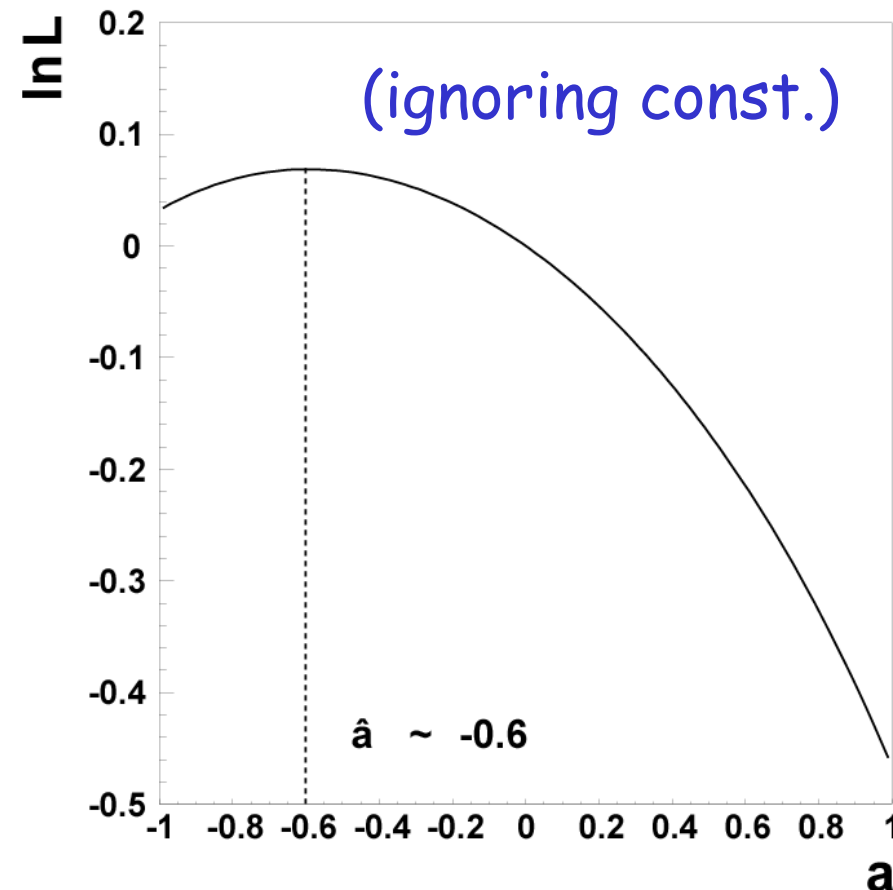
We have $P(0.89)=1+0.39a$ etc

Construct maximum likelihood:

$$\ln L = \ln(1+0.39a) + \ln(1-0.47a) + \ln(1) \\ + \ln(1-0.14a) + \ln(1-0.01a) + \text{const.}$$

Plot this to see it has a maximum
Near $a=0.6$.

So log likelihood estimator is $\hat{a} \sim -0.6$



Important Example: Combining Measurements of the Same Quantity with Different Errors

What is our best estimate of a quantity, which has been measured several times (values x_i) with different errors σ_i ?

For each measurement, i ,

$$P(x_i) = \frac{1}{\sigma_i \sqrt{2\pi}} e^{-(x_i - \mu)^2 / 2\sigma_i^2}$$

So the log likelihood is:

$$\ln L = \sum_i -\ln \sigma_i \sqrt{2\pi} - \sum_i \frac{(x_i - \mu)^2}{2\sigma_i^2}$$

Differentiating:

$$\frac{\partial \ln L}{\partial \mu} = \sum_i \frac{x_i - \mu}{\sigma_i^2} = 0 \quad \text{at maximum}$$

Best estimate of mean is to weight the usual average by (variance)⁻¹ ...

$$\hat{\mu} = \frac{\sum_i (x_i / \sigma_i^2)}{\sum_i (1 / \sigma_i^2)}$$

Can also show that $\hat{\sigma}^2 = \frac{1}{\sum_i (1 / \sigma_i^2)}$

("the weighted mean")