

# Symmetries in Particle Physics



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# Introduction

- In this course, we shall examine how certain types of symmetry can be expressed and applied in Particle Physics.
- Aim is to provide an intuitive approach, without going into rigorous proofs of the results we shall require.

# Books

- Texts used for this course are
  - F. Halzen and A.D. Martin *Quarks and Leptons*, (Wiley, New York, 1984)
  - F.E. Close *An Introduction to Quarks and Partons* (Academic Press, New York, 1978)
  - W.M. Gibson and B.R. Pollard *Symmetry Principles in Elementary Particle Physics* (Cambridge University Press, 1984)
  - H.J. Lipkin *Lie Groups for Pedestrians* (North Holland, Amsterdam, 1965)

# Groups

- (This lecture looks at material mainly in R.R. Stoll *Set Theory and Logic*, W.H. Freeman and Co., San Francisco, 1963)
- Purpose of lecture
  - To define a group
  - Investigate a few elementary properties of groups.

# Definition of a Group

- A group is an ordered triple  $\langle G, \bullet, e \rangle$ , where
  - $G$  is a set
  - $\bullet$  is a binary operation
  - $e$  is a member of  $G$
- 1.  $\bullet$  is an associative operation:  
$$a \bullet (b \bullet c) = (a \bullet b) \bullet c$$
- 2. For each  $a$  in  $G$ ,  $e \bullet a = a$
- 3. For each  $a$  in  $G$ , there exists an element  $a'$  in  $G$  such that  $a' \bullet a = e$

# Group Properties

- $e$  is a neutral element

– *PROOF*

- If  $a$  is in  $G$ ,  $\exists a'$  in  $G$  such that  $a' \bullet a = e$   
and  
 $\exists a''$  such that  $a'' \bullet a' = e$

- Then

$$\begin{aligned} a \bullet a' &= e \bullet (a \bullet a') &&= (a'' \bullet a') \bullet (a \bullet a') \\ &= a'' \bullet (a' \bullet a) \bullet a' &&= a'' \bullet (e \bullet a') \\ &= a'' \bullet a' = e \end{aligned}$$

- So  $e$  must be a neutral element, since

$$a \bullet e = a \bullet (a' \bullet a) = (a \bullet a') \bullet a = e \bullet a = a$$

- Also  $a$  is invertible, since  $a \bullet a' = a' \bullet a = e$

# More Definitions

- If the elements in the group are finite then the group is **finite** and the number of elements is the **order** of the group
- If a group is not **finite**, it is **infinite**.
- If the operation satisfies  $a \bullet b = b \bullet a$ , then the group is **commutative** or **Abelian**.

# Examples

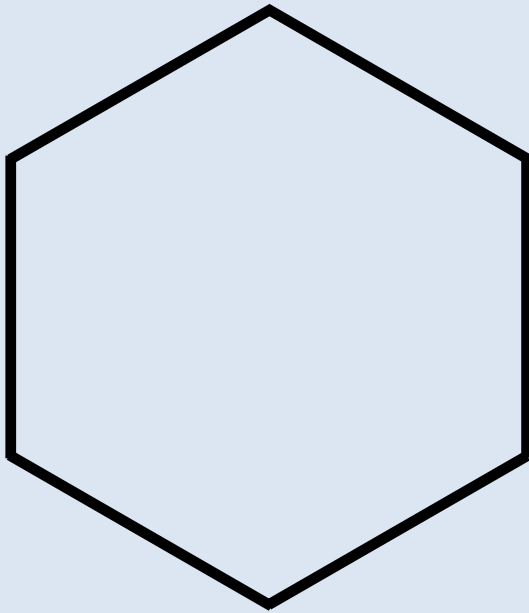
- **Addition**
  - Integers form a group under addition
  - Real numbers form a group under addition
  - Natural numbers?
  - What is the neutral element
- **Multiplication**
  - Real numbers form a group under multiplication
  - Integers?
  - What is the neutral element?
- Are the groups **Abelian** or **non-Abelian**?



# More examples

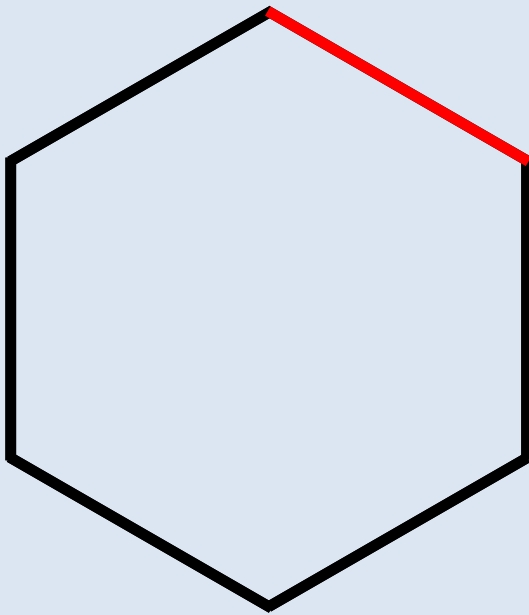
- **Matrices**
  - form an **Abelian** group under addition
  - form a **non-Abelian** group under multiplication
    - ( $\underline{\mathbf{A}} \cdot \underline{\mathbf{B}} \neq \underline{\mathbf{B}} \cdot \underline{\mathbf{A}}$ )
- Most of the lectures will discuss transformations of different kinds (translations, rotations, etc.) and their associated groups.
- At first sight, this does not seem to fit the remit for a group, as transformations are monadic operators:  $\mathbf{T}a = a'$ .
- The theory of groups instead applies to how the transformations themselves are combined. (Non-Abelian groups yield more interesting structures.)

# 1-D Rotations



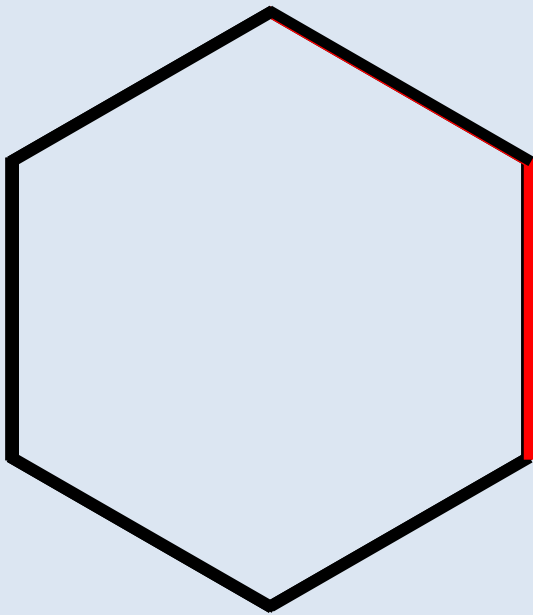
- In order to study rotational symmetry we need to define what it means to have an equivalent system
- Normally means that after the rotation the system is indistinguishable from the original
- We can keep track of this by artificially labelling a feature of the symmetric shape.
- Then when we perform an appropriate rotation, the system remains unchanged (*i.e.* invariant.)
- One dimensional rotations commute  
 $R_A R_B = R_B R_A$

# 1-D Rotations



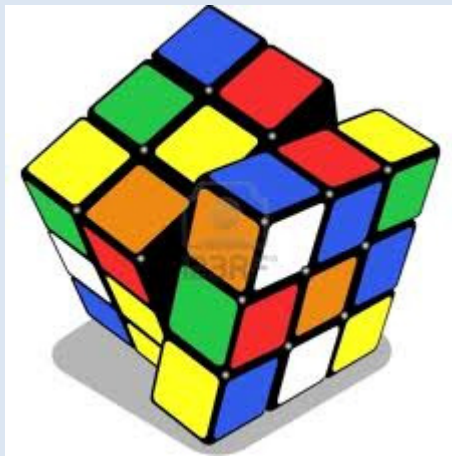
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# 3-D Rotations



- When rotations can take place in more than one plane, order of rotations becomes important
  - Here  $R_A R_B \neq R_B R_A$ , in general.
  - There can be sub-groups with different properties. For example, a sub-class of 1D rotations inside the general 3D rotations clearly *does* commute.
  - Group structure should take this into account.

# Quantum Mechanics

- In order to describe microscopic systems (such as systems of elementary particles) the transformations are described by quantum operators.
- Thus a typical operation would read

$$R|\psi\rangle = \lambda|\psi\rangle$$

and symmetries among operations would depend on whether

$$RQ|\psi\rangle = QR|\psi\rangle \quad \text{or not.}$$